



The Nanometer Optical Component Measuring Machine: a new Sub-nm Topography Measuring Device for X-ray Optics at BESSY

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Motivation

Engineering Conception and Design

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Motivation

The quality of optical components limits the potential performance of a SR-beamline

New optical components beyond the 0.1 arcsec rms limit require metrology tools of 3 - 5 times superior accuracy

A manufacturer independent metrology is essential for a critical inspection of delivered and mounted optical elements

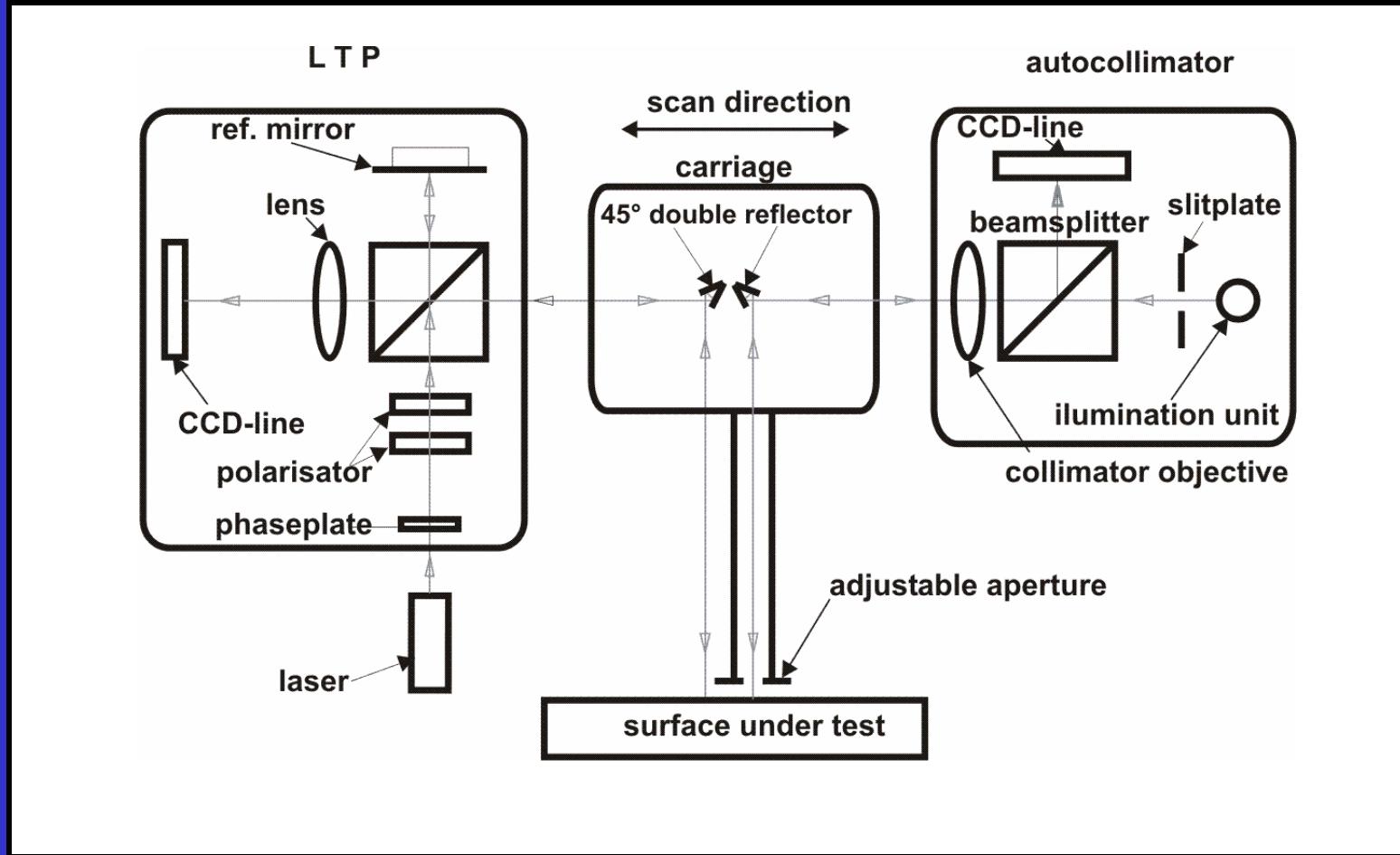
desired specifications of SR-beamline components and required accuracy of metrology tools

surface shape	size	slope error	shape deviation			required measuring uncertainty	
	length		[mm]	[arcsec rms]	[nm rms]	[nm p-v]	
plan	300	0.03	3	10	10	10	1
	150	0.02	1.5	7	6	6	0.5
spherical	300	0.05	3	10	15	15	1
	150	0.03	1.5	7	10	10	0.5
aspherical	300	0.06	6	20	15	15	2
	150	0.05	3	15	10	10	1

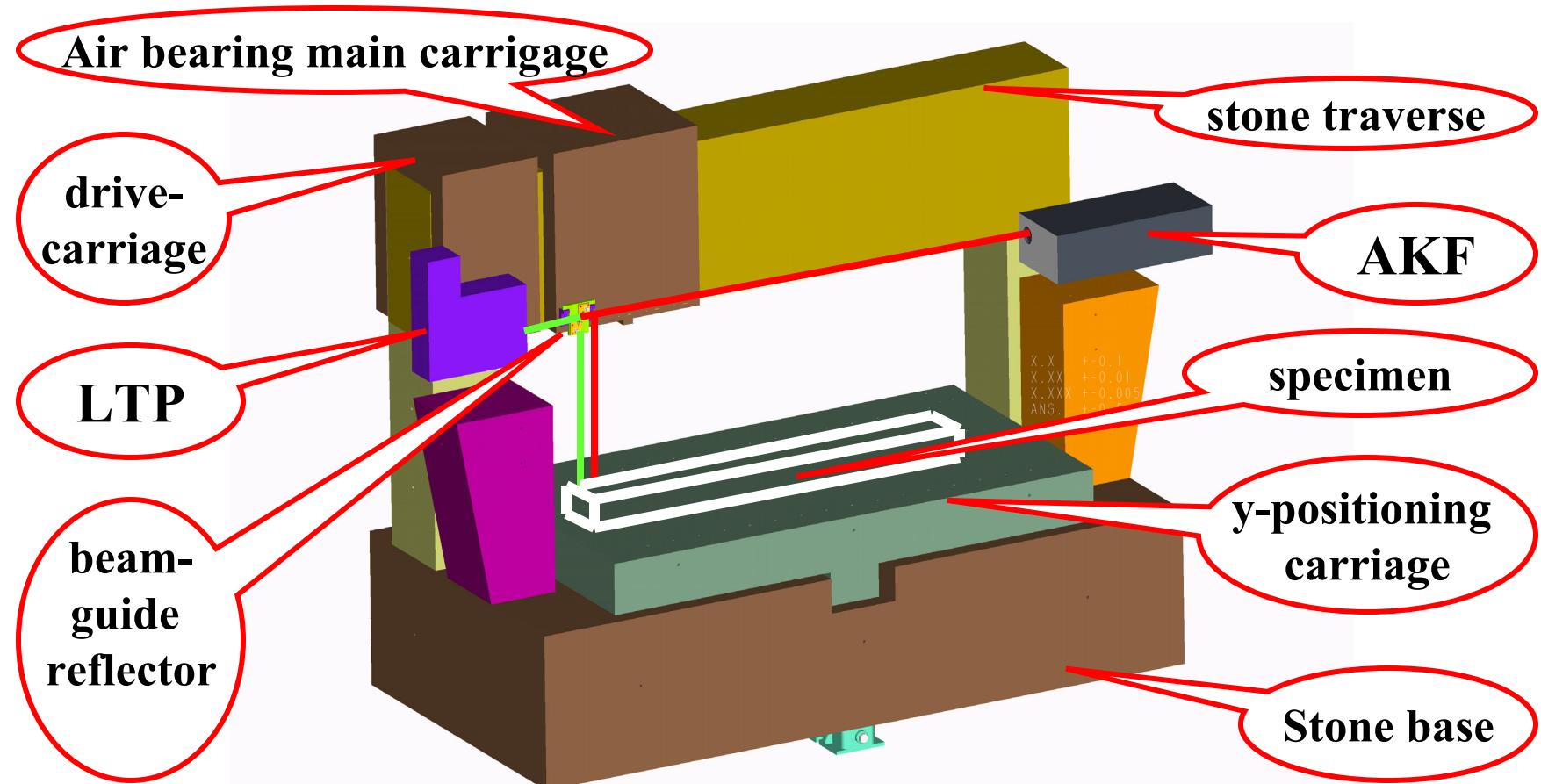


Engineering Conception and Design

Optical set-up scheme of the NOM (side view)



Nanometer Optical component Measurement machine NOM



Stone Table and Carriage System with aerostatic bearings



**Complete head-load of the NOM < 2 W,
Thermal isolation of the NOM by a double walled and thermal-bridge free
housing - low influence of air turbulence on the measurement**

Engineering Conception and Design

**LTP-head and Autocollimator are mounted stationary and opposite to each other
- two 45° double reflectors to guide the test beam to and from the specimen**

**Material of the mechanical parts is stone - total weight: 4 t
high heat capacity, low thermal conductivity, vibration damping - low eigenfrequency**

Measurement carriage with stiffed, preloaded airbearing (low weight double carriage system with torque free coupling)

Complete head-load of the NOM < 2 W

**Thermal isolation of the NOM by a double walled and thermal-bridge free housing
- low influence of air turbulence on the measurement**

Technical Parameter

Measuring area: 1200 mm in length, 300 mm laterally

Accuracy of guidance of the scanning carriage: 1 µm (range of motion: 1.3 m)

Reproducibility of the scanning carriage movement: < 0.01 arcsec rms

Technical Parameter of the NOM-Sensors

	LTP	Autocollimator
view angle	± 6.6 mrad	± 1.5 mrad
measurable radius of curvature	1 m	10 m
spatial resolution	1 mm	2 mm
reflectance	4 – 100 %	4 – 100 %

Software

hardware control

drive (6 axis)
motor parameter
axis control
position control

sensors
implementation of sensor-library
read-out AKF
read-out LTP

measurement

measurement
operating control
time scheduled meas.
measurement of multiple SUT

measuring options
Single-line-, multiple-, or 3d- scan
step-by-step, on-the-fly
autocalibration, automatic adjustment

presentation of results

numerical data

hardcopy print out graphically representation

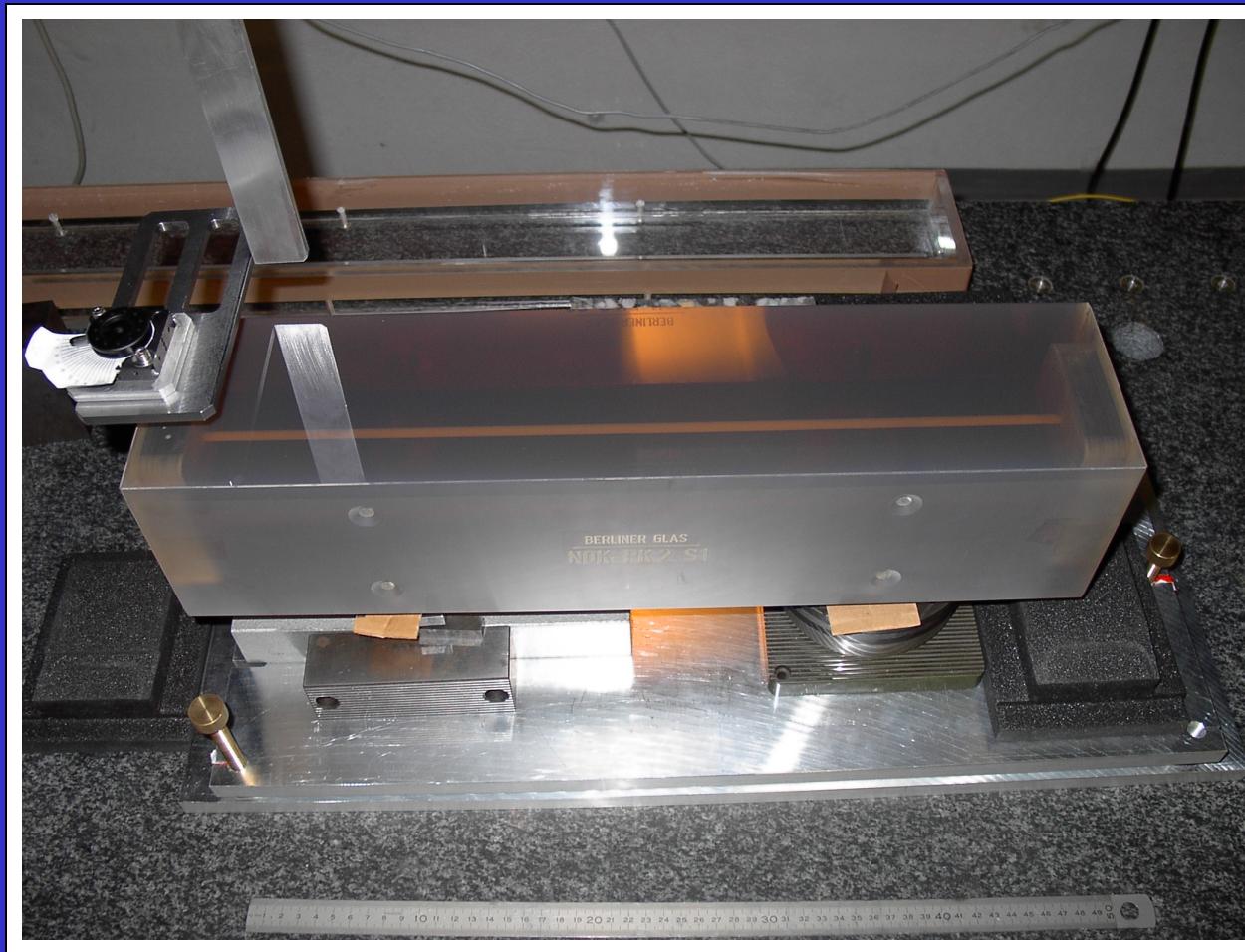


Measurement Results

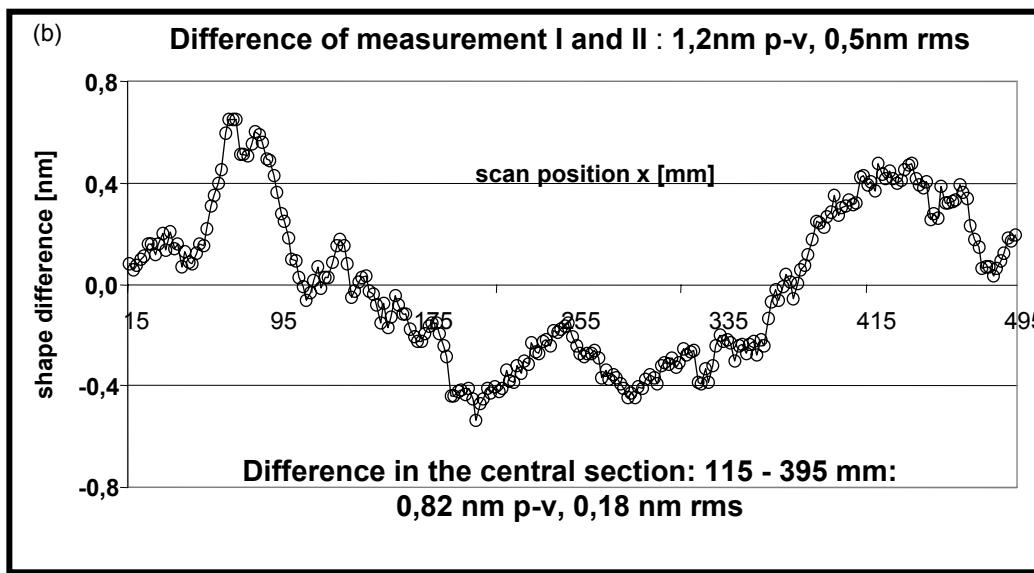
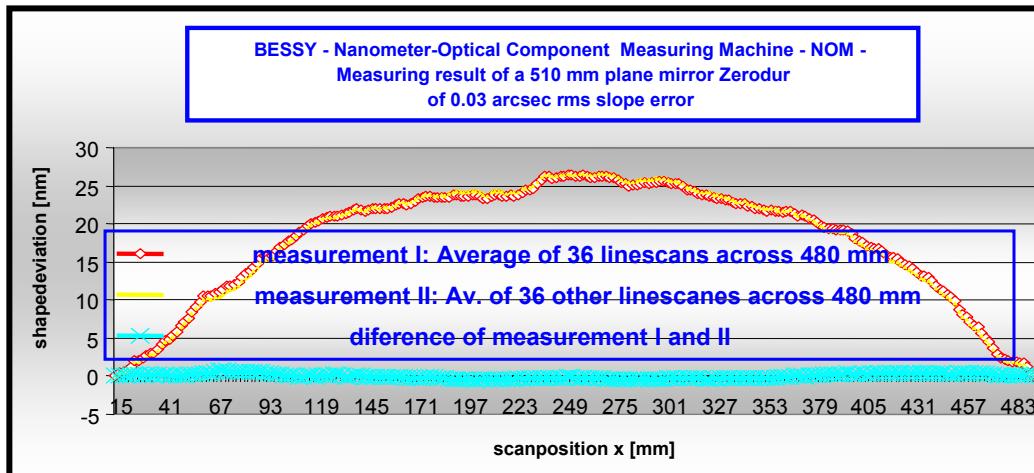
line-scan on a 510mm mirror - substrate material: Zerodur™

Method for 3d-Surface scan

line-scan on a 510mm mirror - substrate material: Zerodur™



NOM (AKF)- Measuring result Zerodur™-specimen 510 mm - Reproducibility



Measuring result:
sagitta:

$(26,5 \pm 1,2)$ nm p-v

$(< \lambda/20) \pm \lambda/1000$ p-v

slope (1 marcsec = 0,001 arcsec) :

$(213 \pm 4,5)$ marcsec p-v

$(33,5 \pm 4,5)$ marcsec rms

Result with circle fit:

radius: - (1083 ± 4) km;

height:

$(4,4 \pm 0,6)$ nm p-v

slope:

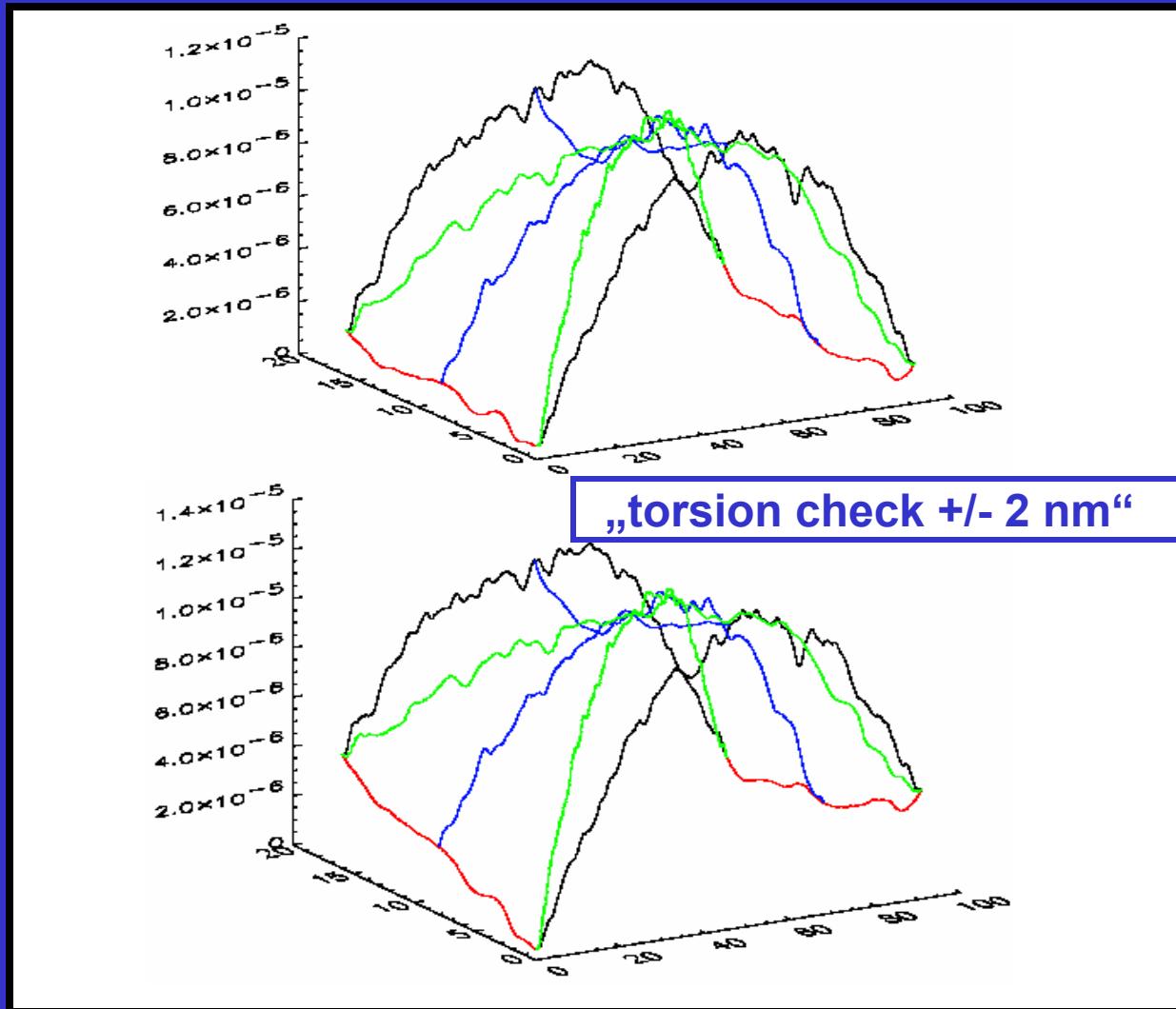
$(20,4 \pm 0,4)$ marcsec rms

$= (98 \pm 2)$ nrad rms

Reproducibility (480 mm)

$< 0,5$ nm rms;

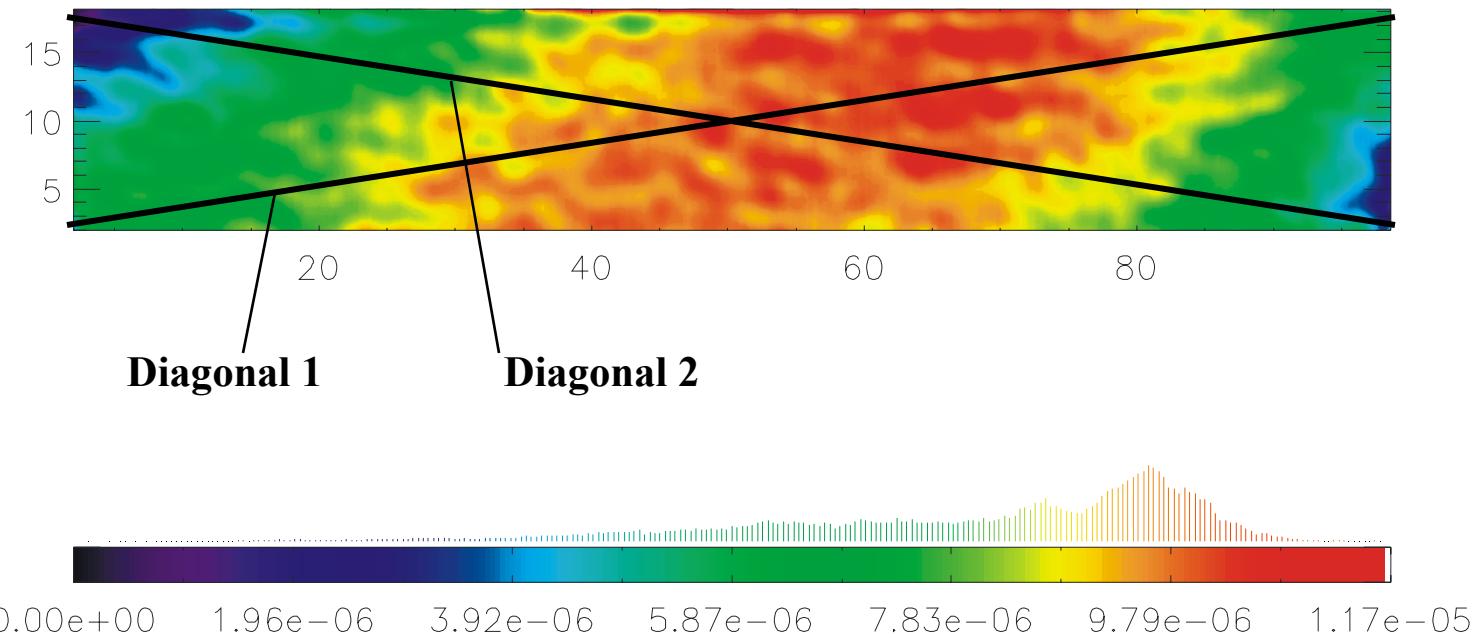
0,2 marcsec rms = 1nrad rms

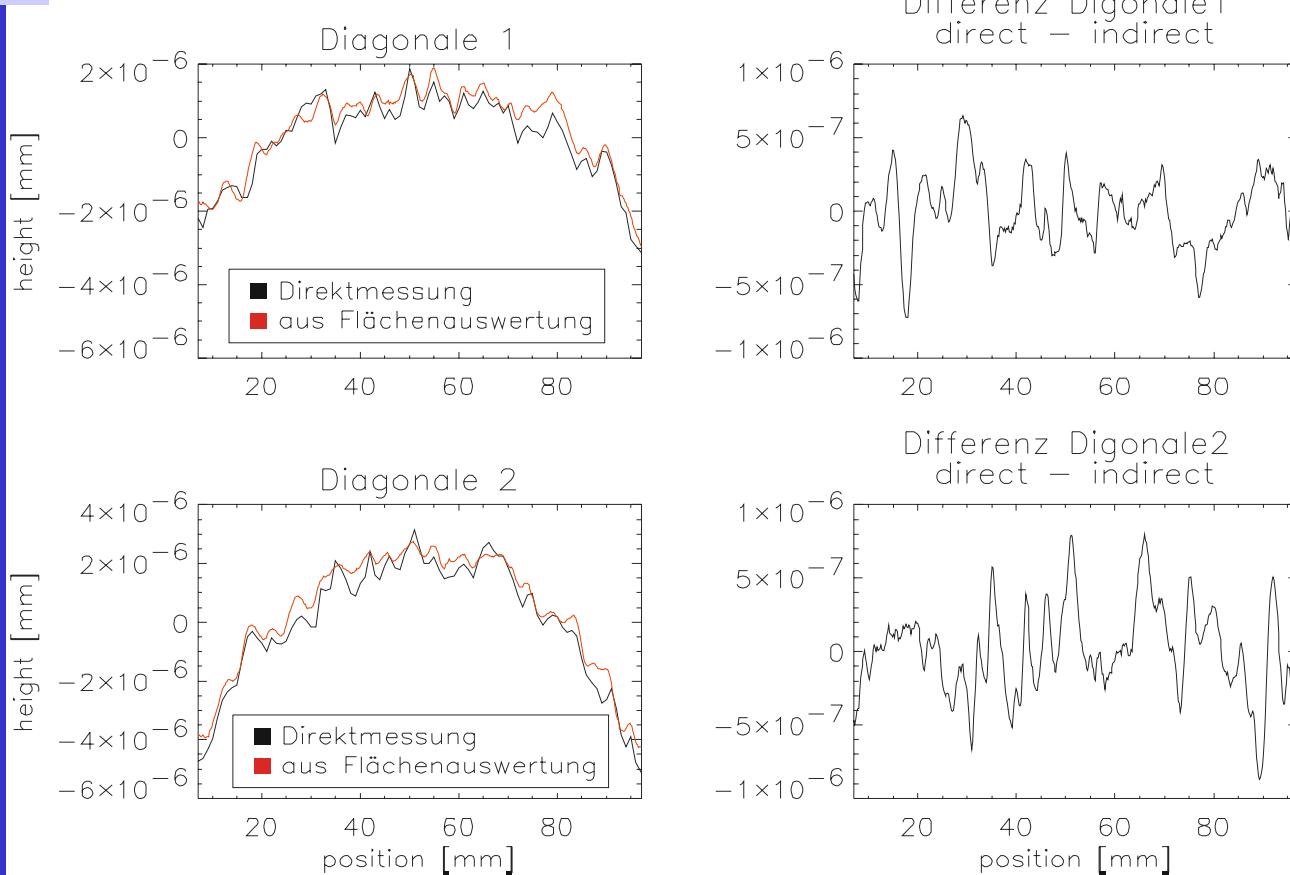


3d-measurement of surfaces

1. surface scans: parallel sampled line-scans in meridional and sagittal direction
2. measurement of the two diagonals as single-line-scan
3. Comparison of direct scanned diagonals with diagonals gained from surface scan

3d-surface-scan
Torsion -5,5nm: conformity of diagonals: 0,29 nm rms
80.000 measuring points, time: 8h
11,8 nm p-v 1,9 nm rms

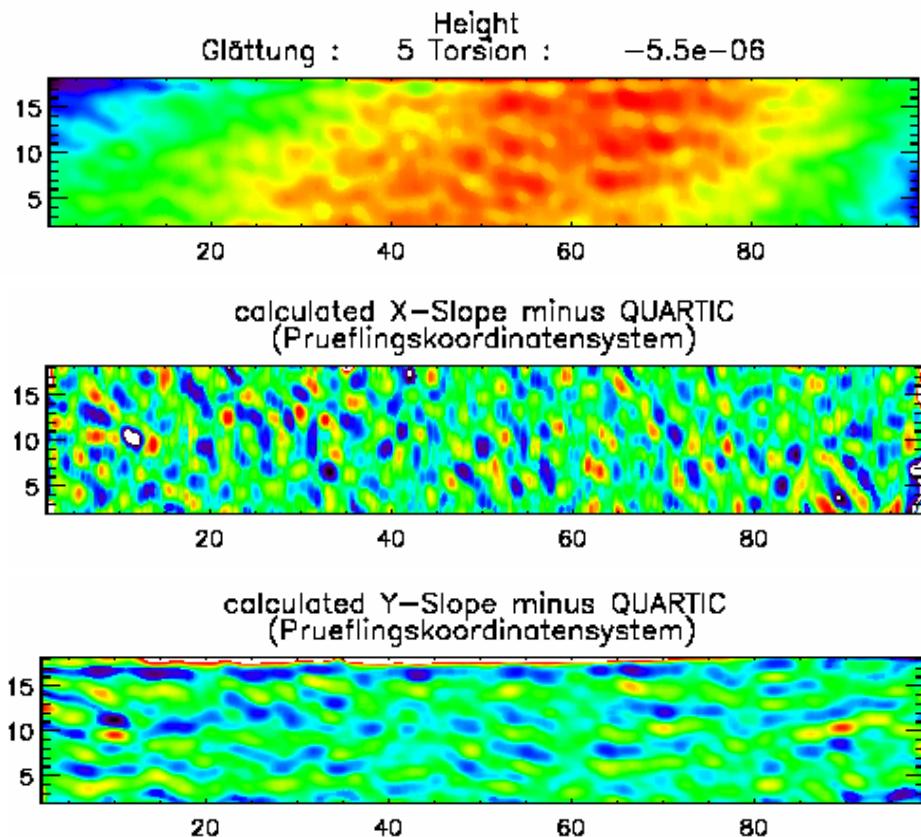
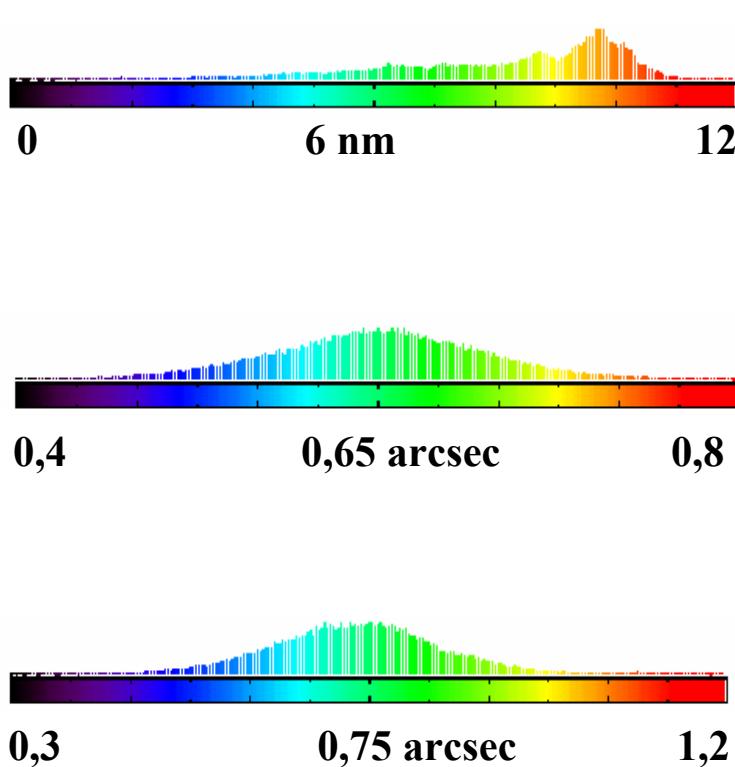




difference diagonals 1 = +/- 0.249 nm

difference diagonals 2 = +/- 0.302 nm

average diagonals 1 and 2 = +/- 0.277 nm



**Map of calculated slope-deviation in meridional and sagittal direction
to view the quality of surfaces regarding use in SR-beamlines**

result of 3-step 3d-measurement:

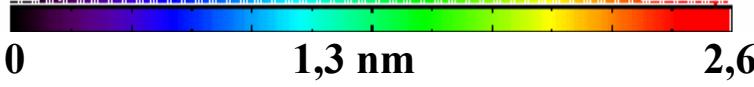
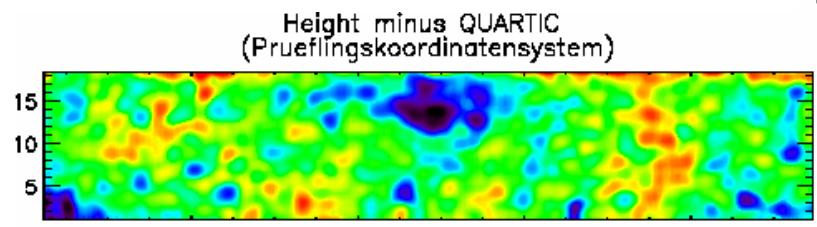
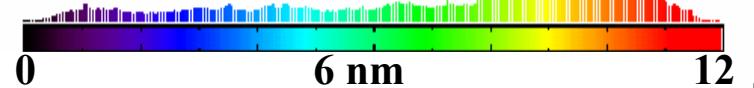
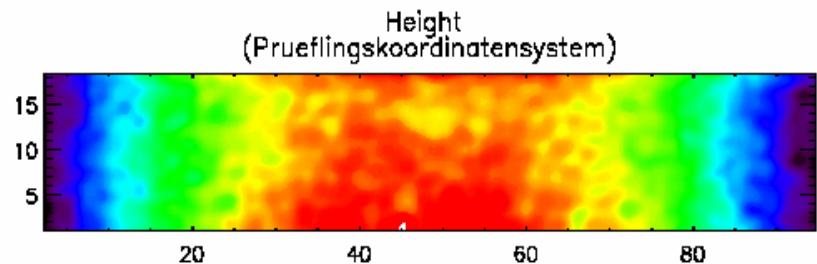
	unfitted	fitted (quartic)
x-slope [arcsec p-v]	2,1	2,1
x-slope [arcsec rms]	0,07	0,06

	unfitted	fitted (quartic)
y-slope [arcsec p-v]	1,9	1,9
y-slope [arcsec rms]	0,14	0,14

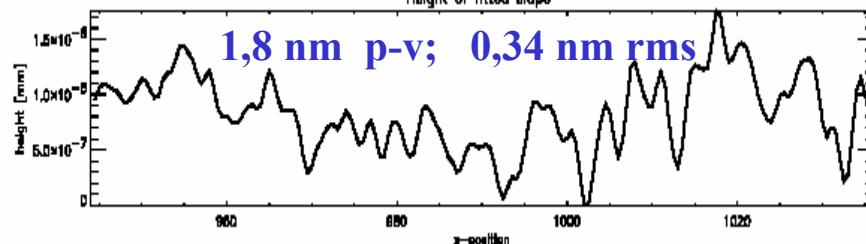
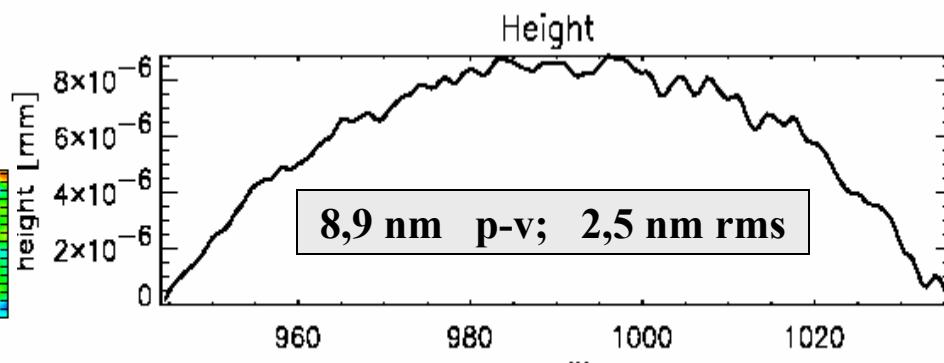
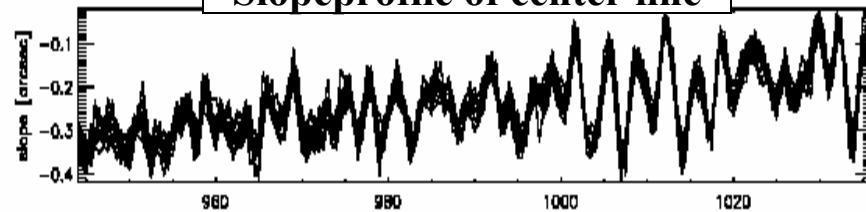
3d and line-scan measurement on a 100mm Si-grating blank

scan length =92 mm; dx=0,5 mm, aperture: 2mm, 3 different x-start (704; 794; 944 mm); 5 AKF-start-angle (-0,3...1,6°)

result of 60 line-scans: (0.074 +/- 0.002) arcsec rms; (0.059 +/- 0.002) m arcsec rms; bestfit: [R = (- 125 +/- 12) km]:

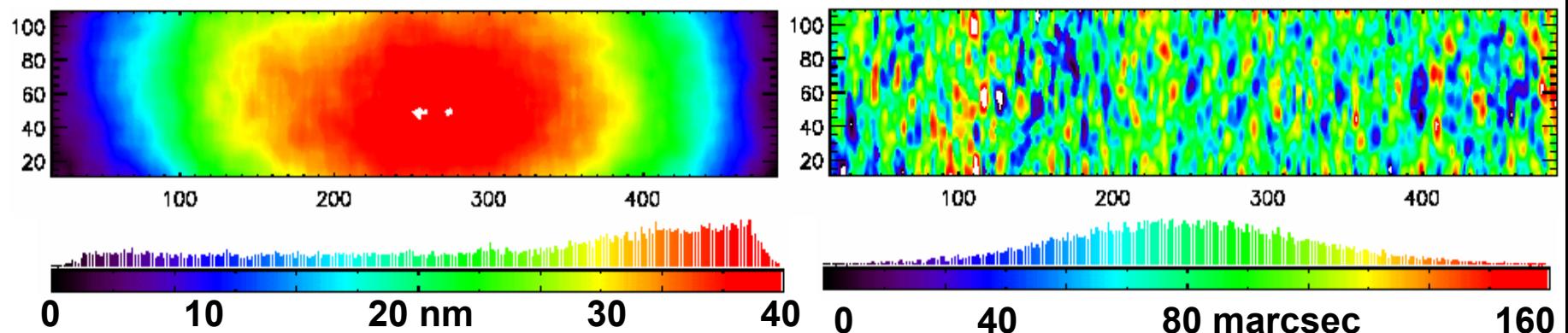


Slopeprofile of center line



3-D-imaging of a 600 cm² plane surface with AKF

height: 40 nm p-v; fit: 1,3 nm rms slope fit: p-v:160; rms: 25 marcsec



Conclusions:

The Hybrid conception of the NOM by use of two different Type Sensors: LTP and Autocollimator has been demonstrated

First measurements demonstrates a estimated measurement uncertainty in the range of 0.01 arcsec rms and a correspondingly high reproducibility

A practicable method for 3d scanning has been developed

Ion beam milling supported by NOM-measurements leads to optical components of previously not achieved quality beyond the 0.1 arcsec rms limit

The development of the NOM is not finished - the application of a new modified autocollimator is intended (free aperture: 1 - 1.5 mm)

The shown state of the NOM represents a five to tenfold improvement compared to the present state of the art of surface measuring techniques.

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